

## Time Counts!

Some comments on system latency  
in head-referenced displays

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### Definition of a Virtual Environment

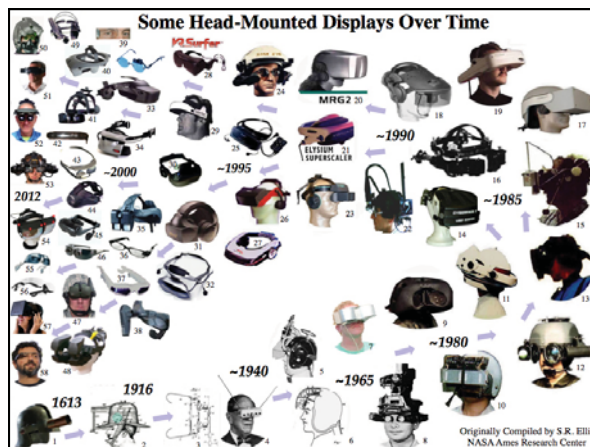
A virtual environment is an interactive, virtual image display enhanced by special processing to convince its users that they are personally and directly physically immersed in a space other than the one they actually inhabit.



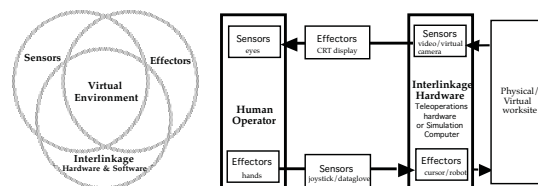
Ivan Sutherland's HMD Univ. of Utah

Ivan Sutherland's virtual environment *personal simulator*<sup>1</sup> circa 1965

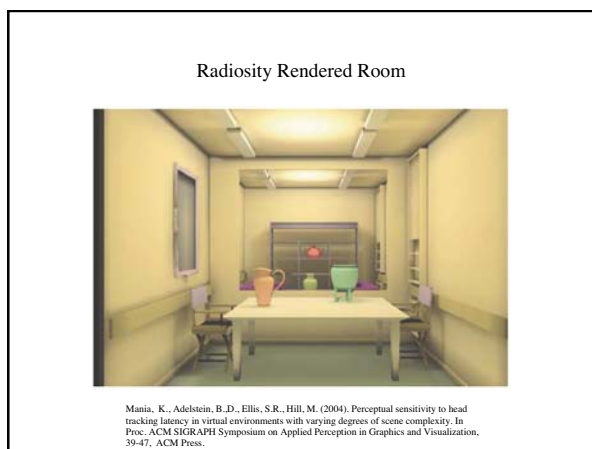
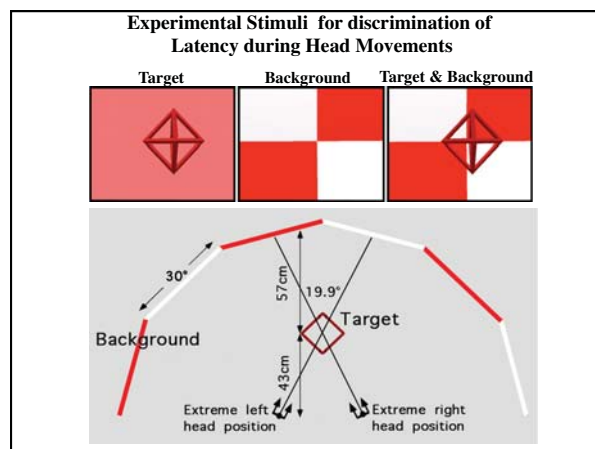
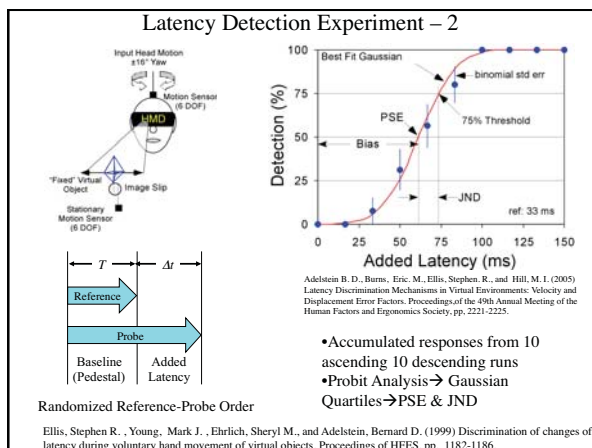
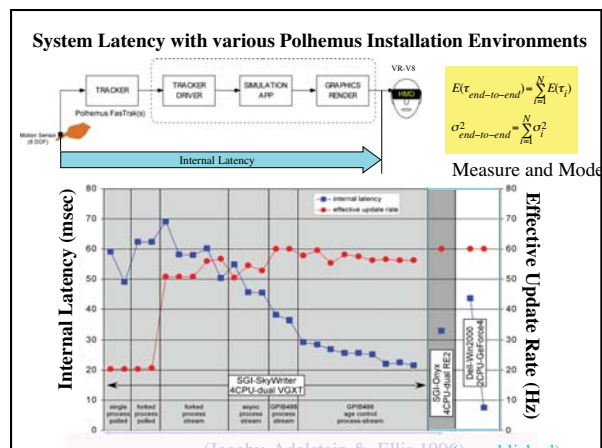
<sup>1</sup>Haber, R. N. (1986). The simulation of high speed aircraft flight. *Scientific American*, 255(July) 96-103.

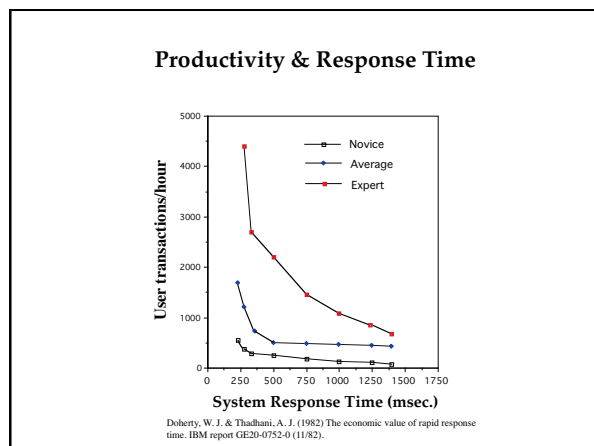
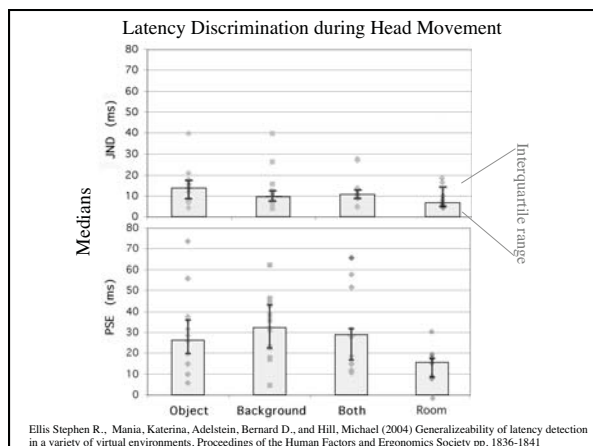


### Decompositions of a Virtual Environment



Ellis, S. R. (1993) What are virtual environments? *Computer Graphics and Applications*, 14, 1, 17-22.





**Some Dream Performance Specs for Virtual Environments and Augmented Reality**

Bi-ocular/stereo optical see-through AR

Light-weight spectacle nonocclusive format

1"/pixel visual resolution

Presenting accurate disparities

Adaptive (or just correct) disparity range w/vergence

> 8 bit/color channel

> 60° full binocular see-through horizontal FOV

Adaptive 15% Luminance increment up to  $3 \times 10^4$  cd/m<sup>2</sup>

Legible 10 pt text @ 30 cm

Embedded fast head, hand & world tracking

< 8 ms image update latency

> 120 Hz image update

Wifi video & data

Mobile phone equivalent bandwidth

Everything else I left out

Thank you for your attention

	Transmission delay	Bandwidth	Resolution	Dynamic range	Signal/noise
Simulation Hardware	<b>Displays</b>				
	<b>Visual</b>				
	20-100 msec	20-100 Hz	2/ pixel w/i 5° central vision	8 bit grey scale/ color	25:1 contrast ratio
	100 msec	0.1-5 Hz	2/ pixel w/i central vision	30° binocular overlap: 2° disparity	120:1 disparity ratio
	5 msec	0-10 K Hz	10-100 micron vibration	8 bit	200:1 RMS ratio
	20 msec	50-100 Hz	1-2 mm spatial resolution	20 N @ DC to 1 N @ 10 Hz	64:1 RMS ratio
	1 msec	20Hz-20 KHz	freq. 0.2-3 Hz	power 2 dB	16 bit
	50-500 msec	3-6 Hz	Directional Sound	relative direction: 1° @ 5° C.E.P.	4x steradians
	10-100 msec	1.5-2 words/sec	Vocal (Synthetic speech)	90-95% recognition in 50,000 word vocab	potentially unlimited
	10 msec	3-10 Hz	Manipulative (Mice, Joysticks, Pedals, Trackers, etc.)	0.2° joint angle	Range: exoskeletal limb motion
Human Operator	<b>Controls</b>				
	1-2 sec	1-2 words/sec	Vocal (Speech Recognition)	<< 5% probability of misrecognition	20,000 words

After Ellis, S. R. (1993) What are virtual environments? *Computer Graphics and Applications*, 14, 1, 17-22.

